


```

c           u(i)= mass*alpha*(r(i)**2-beta**2)**2
c           U(i)= (beta**2*(16*alpha**2*r(i)**2*(-1 + r(i)**2)**2 -
c           & (2*(8*alpha*r(i)**2 + 4*alpha*(-1 + r(i)**2)))/beta))/4.

c           u(i)= 10.*(r(i)**2-1.**2)**2

           U(i) = 0.5*mass*alpha**2*(r(i))**2

           write(13,*) r(i), U(i)
           if (dim.eq.3) u(i)=u(i)+elle*(elle+1.)/r(i)**2
           end do

cccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccc
c      matrice da diagonalizzare
cccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccc
do j=1,k
  do i=1,k
    a(j,i)=0.
  end do
end do
a(1,1)=u(1)+2./dr**2/2.
a(1,2)=-1./dr**2/2.
do j=2,k-1
  a(j,j-1)=-1./dr**2/2.
  a(j,j)=2./dr**2/2.+u(j)
  a(j,j+1)=-1./dr**2/2.
end do
a(k,k-1)=-1./dr**2/2.
a(k,k)=2./dr**2/2.+u(k)

cccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccc
c      chiama la routine per autovalori e autovettori
cccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccc
print *,'
print *,' ... sto calcolando ....'
matz=1 ! (opzione unica: autovalori e autovettori)
call rs (k,k,a, eval,matz,evec,fv1,fv2,ierr)
cccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccc
c      risultati
cccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccccc
print *,'
print *,' ..... fatto ! '
print *,'
print *,' primi 6 autovalori :'
do i=1,6
  print *,i,' ----> ',eval(i)
end do
print *,'
print *,' autovalori in EIGENVALUES.DAT '
print *,' autovettori in EIGENVECTORS.DAT '
print *,'
open(unit=1,file='eigenvectors.dat',status='unknown')
do i=1,k
  if(dim.eq.3) then

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c      ierr  is an integer output variable set equal to an error
c          completion code described in the documentation for tqlrat
c          and tql2.  the normal completion code is zero.
c
c      fv1  and  fv2  are temporary storage arrays.
c
c      questions and comments should be directed to burton s. garbow,
c      mathematics and computer science div, argonne national laboratory
c
c      this version dated august 1983.
c
c -----
c
c      if (n .le. nm) go to 10
c      ierr = 10 * n
c      go to 50
c
c 10 if (matz .ne. 0) go to 20
c      ..... find eigenvalues only .....           (enabled !!)
c      call tred1(nm,n,a,w,fv1,fv2)
c      tqlrat encounters catastrophic underflow on the Vax
c      call tqlrat(n,w,fv2,ierr)
c      call tql1(n,w,fv1,ierr)
c      go to 50
c      ..... find both eigenvalues and eigenvectors .....
c 20 call tred2(nm,n,a,w,fv1,z)
c      call tql2(nm,n,w,fv1,z,ierr)
c 50 return
c      end
c      subroutine tred2(nm,n,a,d,e,z)
c
c      integer i,j,k,l,n,ni,nm,jp1
c      double precision a(nm,n),d(n),e(n),z(nm,n)
c      double precision f,g,h,hh,scale
c
c      this subroutine is a translation of the algol procedure tred2,
c      num. math. 11, 181-195(1968) by martin, reinsch, and wilkinson.
c      handbook for auto. comp., vol.ii-linear algebra, 212-226(1971).
c
c      this subroutine reduces a real symmetric matrix to a
c      symmetric tridiagonal matrix using and accumulating
c      orthogonal similarity transformations.
c
c      on input
c
c      nm must be set to the row dimension of two-dimensional
c      array parameters as declared in the calling program
c      dimension statement.
c
c      n is the order of the matrix.
c
c      a contains the real symmetric input matrix.  only the
c      lower triangle of the matrix need be supplied.
c
c      on output

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c
c      d contains the diagonal elements of the tridiagonal matrix.
c
c      e contains the subdiagonal elements of the tridiagonal
c          matrix in its last n-1 positions.  e(1) is set to zero.
c
c      z contains the orthogonal transformation matrix
c          produced in the reduction.
c
c      a and z may coincide.  if distinct, a is unaltered.
c
c      questions and comments should be directed to burton s. garbow,
c      mathematics and computer science div, argonne national laboratory
c
c      this version dated august 1983.
c
c      -----
c
c      do 100 i = 1, n
c
c          do 80 j = i, n
c              z(j,i) = a(j,i)
c
c          d(i) = a(n,i)
c 100 continue
c
c      if (n .eq. 1) go to 510
c      ..... for i=n step -1 until 2 do -- .....
c      do 300 ii = 2, n
c          i = n + 2 - ii
c          l = i - 1
c          h = 0.0d0
c          scale = 0.0d0
c          if (l .lt. 2) go to 130
c          ..... scale row (algol tol then not needed) .....
c          do 120 k = 1, l
c              scale = scale + dabs(d(k))
c
c          if (scale .ne. 0.0d0) go to 140
c 130   e(i) = d(l)
c
c          do 135 j = 1, l
c              d(j) = z(l,j)
c              z(i,j) = 0.0d0
c              z(j,i) = 0.0d0
c 135   continue
c
c          go to 290
c
c 140   do 150 k = 1, l
c              d(k) = d(k) / scale
c              h = h + d(k) * d(k)
c 150   continue
c
c          f = d(l)

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g = -dsign(dsqr(h),f)
e(i) = scale * g
h = h - f * g
d(l) = f - g
c ..... form a*u .....
do 170 j = 1, l
170 e(j) = 0.0d0
c
do 240 j = 1, l
f = d(j)
z(j,i) = f
g = e(j) + z(j,j) * f
jp1 = j + 1
if (l .lt. jp1) go to 220
c
do 200 k = jp1, l
g = g + z(k,j) * d(k)
e(k) = e(k) + z(k,j) * f
200 continue
c
220 e(j) = g
240 continue
c ..... form p .....
f = 0.0d0
c
do 245 j = 1, l
e(j) = e(j) / h
f = f + e(j) * d(j)
245 continue
c
hh = f / (h + h)
c ..... form q .....
do 250 j = 1, l
250 e(j) = e(j) - hh * d(j)
c ..... form reduced a .....
do 280 j = 1, l
f = d(j)
g = e(j)
c
do 260 k = j, l
260 z(k,j) = z(k,j) - f * e(k) - g * d(k)
c
d(j) = z(l,j)
z(i,j) = 0.0d0
280 continue
c
290 d(i) = h
300 continue
c ..... accumulation of transformation matrices .....
do 500 i = 2, n
l = i - 1
z(n,l) = z(l,l)
z(l,l) = 1.0d0
h = d(i)
if (h .eq. 0.0d0) go to 380

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c
      do 330 k = 1, l
330    d(k) = z(k,i) / h
c
      do 360 j = 1, l
      g = 0.0d0
c
      do 340 k = 1, l
340    g = g + z(k,i) * z(k,j)
c
      do 360 k = 1, l
      z(k,j) = z(k,j) - g * d(k)
360    continue
c
380    do 400 k = 1, l
400    z(k,i) = 0.0d0
c
500 continue
c
510 do 520 i = 1, n
      d(i) = z(n,i)
      z(n,i) = 0.0d0
520 continue
c
z(n,n) = 1.0d0
e(1) = 0.0d0
return
end
subroutine tql2(nm,n,d,e,z,ierr)
c
integer i,j,k,l,m,n,ii,l1,l2,nm,mml,ierr
double precision d(n),e(n),z(nm,n)
double precision c,c2,c3,dl1,el1,f,g,h,p,r,s,s2,tst1,tst2,pythag
c
c this subroutine is a translation of the algol procedure tql2,
c num. math. 11, 293-306(1968) by bowdler, martin, reinsch, and
c wilkinson.
c handbook for auto. comp., vol.ii-linear algebra, 227-240(1971).
c
c this subroutine finds the eigenvalues and eigenvectors
c of a symmetric tridiagonal matrix by the ql method.
c the eigenvectors of a full symmetric matrix can also
c be found if tred2 has been used to reduce this
c full matrix to tridiagonal form.
c
c on input
c
c      nm must be set to the row dimension of two-dimensional
c          array parameters as declared in the calling program
c          dimension statement.
c
c      n is the order of the matrix.
c      ~
c      d contains the diagonal elements of the input matrix.
c
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c      e contains the subdiagonal elements of the input matrix
c          in its last n-1 positions.  e(1) is arbitrary.
c
c      z contains the transformation matrix produced in the
c          reduction by tred2, if performed.  if the eigenvectors
c          of the tridiagonal matrix are desired, z must contain
c          the identity matrix.
c
c      on output
c
c      d contains the eigenvalues in ascending order.  if an
c          error exit is made, the eigenvalues are correct but
c          unordered for indices 1,2,...,ierr-1.
c
c      e has been destroyed.
c
c      z contains orthonormal eigenvectors of the symmetric
c          tridiagonal (or full) matrix.  if an error exit is made,
c          z contains the eigenvectors associated with the stored
c          eigenvalues.
c
c      ierr is set to
c          zero      for normal return,
c          j        if the j-th eigenvalue has not been
c                      determined after 30 iterations.
c
c      calls pythag for dsqrt(a*a + b*b) .
c
c      questions and comments should be directed to burton s. garbow,
c          mathematics and computer science div, argonne national laboratory
c
c      this version dated august 1983.
c
c -----
c
c      ierr = 0
c      if (n .eq. 1) go to 1001
c
c      do 100 i = 2, n
c 100 e(i-1) = e(i)
c
c      f = 0.0d0
c      tst1 = 0.0d0
c      e(n) = 0.0d0
c
c      do 240 l = 1, n
c          j = 0
c          h = dabs(d(l)) + dabs(e(l))
c          if (tst1 .lt. h) tst1 = h
c
c          ..... look for small sub-diagonal element .....
c          do 110 m = l, n
c              tst2 = tst1 + dabs(e(m))
c              if (tst2 .eq. tst1) go to 120
c
c          ..... e(n) is always zero, so there is no exit
c              through the bottom of the loop .....

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110      continue
c
120      if (m .eq. l) go to 220
130      if (j .eq. 30) go to 1000
         j = j + 1
c      ..... form shift .....
         l1 = l + 1
         l2 = l1 + 1
         g = d(l)
         p = (d(l1) - g) / (2.0d0 * e(l))
         r = pythag(p,1.0d0)
         d(l) = e(l) / (p + dsign(r,p))
         d(l1) = e(l) * (p + dsign(r,p))
         dl1 = d(l1)
         h = g - d(l)
         if (l2 .gt. n) go to 145
c
         do 140 i = l2, n
140      d(i) = d(i) - h
c
145      f = f + h
c      ..... ql transformation .....
         p = d(m)
         c = 1.0d0
         c2 = c
         el1 = e(l1)
         s = 0.0d0
         mml = m - l
c      ..... for i=m-1 step -1 until l do --
         do 200 ii = 1, mml
             c3 = c2
             c2 = c
             s2 = s
             i = m - ii
             g = c * e(i)
             h = c * p
             r = pythag(p,e(i))
             e(i+1) = s * r
             s = e(i) / r
             c = p / r
             p = c * d(i) - s * g
             d(i+1) = h + s * (c * g + s * d(i))
c      ..... form vector .....
         do 180 k = 1, n
             h = z(k,i+1)
             z(k,i+1) = s * z(k,i) + c * h
             z(k,i) = c * z(k,i) - s * h
180      continue
c
200      continue
c
         p = -s * s2 * c3 * el1 * e(l) / dl1
         e(l) = s * p
         d(l) = c * p
         tst2 = tst1 + dabs(e(l))

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```

        if (tst2 .gt. tst1) go to 130
220    d(l) = d(l) + f
240 continue
c       ..... order eigenvalues and eigenvectors .....
do 300 ii = 2, n
    i = ii - 1
    k = i
    p = d(i)
c
    do 260 j = ii, n
        if (d(j) .ge. p) go to 260
        k = j
        p = d(j)
260    continue
c
    if (k .eq. i) go to 300
    d(k) = d(i)
    d(i) = p
c
    do 280 j = 1, n
        p = z(j,i)
        z(j,i) = z(j,k)
        z(j,k) = p
280    continue
c
300 continue
c
    go to 1001
c       ..... set error -- no convergence to an
c           eigenvalue after 30 iterations .....
1000 ierr = l
1001 return
    end
*****
double precision function pythag(a,b)
double precision a,b
c
c   finds dsqrt(a**2+b**2) without overflow or destructive underflow
c
double precision p,r,s,t,u
p = dmax1(dabs(a),dabs(b))
if (p .eq. 0.0d0) go to 20
r = (dmin1(dabs(a),dabs(b))/p)**2
10 continue
    t = 4.0d0 + r
    if (t .eq. 4.0d0) go to 20
    s = r/t
    u = 1.0d0 + 2.0d0*s
    p = u*p
    r = (s/u)**2 * r
    go to 10
20 pythag = p
return
end

```